

On the existence of solutions for a class of systems of functional integral equations of Volterra type in two variables

R. Allahyari¹, R. Arab^{2*} and A. Shole Haghhigh²

¹Department of Mathematics, Mashhad Branch, Islamic Azad University, Mashhad, Iran

²Department of Mathematics, Sari Branch, Islamic Azad University, Sari, Iran

E-mail: mathreza.arab@iausari.ac.ir

Abstract

The aim of this paper is to show how some measures of noncompactness in the Banach space of continuous functions defined on two variables can be applied to the solvability of a general system of functional integral equations. The results obtained generalize and extend several equations. An illustrative example is also presented.

Keywords: Measure of noncompactness; modulus of continuity; system of integral equations

1. Introduction

Measures of noncompactness are very useful tools in the functional analysis. They are also used in the studies of general functional equations, ordinary and partial differential equations, fractional partial differential equations, integral equations, optimal control theory (Kominek et al., 1974; Kordylewski et al., 1960; Kuczma et al., 1960; Matkowsky et al., 1974; O'Regan et al., 1998; O'Regan, 1996; Szepl 1971), for example. Recently, several authors have investigated the existence and behavior of solutions of Volterra type integral equations using the technique of measure of noncompactness (Agarwal et al., 2000; Agarwal et al., 2009; Banas et al., 2009; Darwish 2007; Darwish 2008; Darwish 2009; Estrada et al., 1999). Aghajani et al., in (2011), obtained some results on the existence and behavior of solutions of a class of nonlinear Volterra singular integral equations of the form

$$x(t) = f_1(t, x(t), x(a(t))) + (Gx)(t) \int_0^t f_2(t, s) (Qx)(s) ds,$$

and Darwish and Ntouyas in (2011) obtained similar results on quadratic integral equations. Also, Banas and Dhage in (2008), Banas and Rzepka in (2003), Hu and Yan in (2006), Liu and Kang in (2007) and Liu and Guo in (2005) studied the existence and behavior of solutions of integral equation of solutions of one variable integral equation of Volterra type on the unbounded interval. Aghajani and Jalilian in (2010) extended

results of Banas and Dhage in (2008) by considering the following general form of integral equation $x(t) = f(t, x(\alpha(t)), \int_0^{\beta(t)} g(t, s, x(\gamma(s))) ds$.

Moreover, the problem of existence of solutions for a system of integral equation has been studied by many authors, see (Agarwal et al., 2000; Aghajani et al., 2011; Aghajani et al., To appear; Mursaleen et al., 2012; Mursaleen et al., 2012; Olszowy 2009) and references therein. The object of this paper is to discuss the existence of continuous solutions to the system of nonlinear integral equations

$$x_i(t, s) = f_i(t, s, x_1(t, s), \dots, x_n(t, s), \int_0^{\zeta_i(s)} \int_0^{\beta_i(t)} g_i(t, s, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw), t, s \in R_+, 1 \leq i \leq n,$$

where f_i, g_i, ζ_i and $\beta_i, i = 1, \dots, n$, are continuous functions which satisfy some certain conditions, specified later. To do this, first we state and prove some existing theorems for a general system of equations involving condensing operators, which extend some results of Aghajani et al., in (2013) and generalize the main result of Rzepcki in (1982). Then using the obtained results, we investigate the problem of existence of solutions for system (1).

2. Preliminaries

The concept of measure of noncompactness was initiated by the fundamental paper of Kuratowski in

*Corresponding author

Received: 16 May 2014 / Accepted: 21 January 2015

(1930). In a metric space X , the Kuratowski measure of noncompactness of a subset $S \subset X$ is defined as

$$\alpha(S) := \inf \{ \delta > 0 \mid S = \bigcup_{i=1}^n S_i \text{ for some } S_i \text{ with } \text{diam}(S_i) \leq \delta \text{ for } 1 \leq i \leq n < \infty \}. \quad (2)$$

Here $\text{diam}(T)$ denotes the diameter of a set $T \subset X$, namely $\text{diam}(T) := \sup \{ d(x, y) \mid x, y \in T \}$.

Now, we recall some basic facts concerning measures of noncompactness from Banas et al., in (1980). Denote by \mathbb{R} the set of real numbers and put $\mathbb{R}_+ = [0, +\infty)$. Let $(E, \|\cdot\|)$ be a Banach space with zero element 0. The symbol \overline{X} , $\text{Conv}X$ will denote the closure and closed convex hull of a subset X of E , respectively. Moreover, let \mathfrak{M}_E indicate the family of all nonempty and bounded subsets of E and \mathfrak{N}_E indicate the family of all nonempty and relatively compact sets. We use the following definition of the measure of noncompactness given Banas et al. in (1980).

Definition 1. A mapping $\mu : \mathfrak{M}_E \rightarrow \mathbb{R}_+$ is said to be a measure of noncompactness in E if it satisfies the following conditions:

- 1°. The family $\ker \mu = \{ X \in \mathfrak{M}_E : \mu(X) = 0 \}$ is nonempty and $\ker \mu = \mathfrak{N}_E$.
- 2°. $X \subset Y \Rightarrow \mu(X) \leq \mu(Y)$.
- 3°. $\mu(\overline{X}) = \mu(X)$.
- 4°. $\mu(\text{Conv}X) = \mu(X)$.
- 5°. $\mu(\lambda X + (1-\lambda)Y) \leq \lambda\mu(X) + (1-\lambda)\mu(Y)$ for $\lambda \in [0, 1]$.
- 6°. If $\{X_n\}$ is a sequence of closed sets from \mathfrak{M}_E such that $X_{n+1} \subset X_n$ for $n = 1, 2, \dots$ and if $\lim_{n \rightarrow \infty} \mu(X_n) = 0$, then $X_\infty = \bigcap_{n=1}^\infty X_n \neq \emptyset$.

We need the following theorem that proved Aghajani et al., in (2013), which guarantees the existence of a fixed point for condensing operators (i.e. mappings under which the image of any set is in a certain sense more compact than the set itself) on bounded, closed and convex subsets of a Banach space E .

Theorem 1. (Aghajani et al., 2013) Let Ω be a nonempty, bounded, closed and convex subset of a Banach space E and let $F : \Omega \rightarrow \Omega$ be a continuous mapping such that

$$\mu(FX) \leq \varphi(\mu(X)) \quad (3)$$

for any nonempty subset X of Ω where μ is an arbitrary measure of noncompactness and $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ is a nondecreasing functions such that $\lim_{n \rightarrow \infty} \varphi^n(t) = 0$ for each $t \geq 0$. Then F has at least one fixed point in the set Ω .

The following theorems and examples are basic to all the results of this work.

Theorem 2. (Banas et al., 1980) Suppose $\mu_1, \mu_2, \dots, \mu_n$ are measures of noncompactness in Banach spaces E_1, E_2, \dots, E_n respectively. Moreover assume that the function $F : \mathbb{R}_+^n \rightarrow \mathbb{R}_+$ is convex and $F(x_1, \dots, x_n) = 0$ if and only if $x_i = 0$ for $i = 1, 2, \dots, n$. Then

$$\mu(X) = F(\mu_1(X_1), \mu_2(X_2), \dots, \mu_n(X_n))$$

defines a measure of noncompactness in $E_1 \times E_2 \times \dots \times E_n$ where X_i denotes the natural projection of X into E_i for $i = 1, 2, \dots, n$.

As a result of Theorem 2 we present the following example.

Example 1. Let μ_i ($i = 1, 2, \dots, n$) be measures of noncompactness in Banach spaces E_1, E_2, \dots, E_n respectively, considering $F_1(x_1, \dots, x_n) = k \max_{1 \leq i \leq n} x_i$ and $F_2(x_1, \dots, x_n) = k(x_1 + \dots + x_n)$, $k \in \mathbb{R}_+$ for any $(x_1, \dots, x_n) \in \mathbb{R}_+^n$, then all the conditions of Theorem 2.2 are satisfied. Therefore, $\mu_1 := k \max_{1 \leq i \leq n} \mu(X_i)$ and $\mu_2 := k(\mu(X_1) + \dots + \mu(X_n))$ define measures of noncompactness in the space $E_1 \times E_2 \times \dots \times E_n$ where X_i , $i = 1, 2, \dots, n$ denote the natural projections of X into E_i .

3. Main results

In this section, we state and prove an existence theorem of solutions for a system of equations involving condensing operators in Banach spaces which will be used in section 4 to study the system of nonlinear integral equations (1).

Theorem 3. Let C_i be a nonempty, bounded, convex and closed subset of a Banach space E_i ($i = 1, 2, \dots, n$), and let $F_i : C_1 \times C_2 \times \dots \times C_n \rightarrow C_i$ ($i = 1, 2, \dots, n$) be a continuous operator such that

for any subset X_i of C_i

$$\mu(F_i(X_1 \times X_2 \times \dots \times X_n)) \leq \varphi(\max_i \mu(X_j)) \quad (4)$$

where μ_i is an arbitrary measure of noncompactness on E_i ($i = 1, 2, \dots, n$) and $\varphi: \mathbb{R}_+ \rightarrow \mathbb{R}_+$ is a nondecreasing function such that $\lim_{n \rightarrow \infty} \varphi^n(t) = 0$ for each $t \geq 0$. Then there exist $(x_1^*, x_2^*, \dots, x_n^*) \in C_1 \times C_2 \times \dots \times C_n$ such that for all $1 \leq i \leq n$

$$F_i(x_1^*, x_2^*, \dots, x_n^*) = x_i^*. \quad (5)$$

Proof: Define $F: C_1 \times C_2 \times \dots \times C_n \rightarrow C_1 \times C_2 \times \dots \times C_n$ as follows

$$\begin{aligned} F(x_1, x_2, \dots, x_n) = & (F_1(x_1, x_2, \dots, x_n), \\ & F_2(x_1, x_2, \dots, x_n), \dots, \\ & F_n(x_1, x_2, \dots, x_n)). \end{aligned}$$

Also, consider the measure of noncompactness μ on $E_1 \times E_2 \times \dots \times E_n$ defined by $\mu(X) = \max_i \mu(X_i)$, for any bounded subset $X \subset E_1 \times E_2 \times \dots \times E_n$, where X_i ($i = 1, 2, \dots, n$) denote the natural projections of X into E_i (see Example 2.1). It is obvious that F is continuous. Now we show that F satisfies (3). To prove this, let X be any nonempty and bounded subset of $C_1 \times C_2 \times \dots \times C_n$. Then by (2°) and (4), we obtain

$$\begin{aligned} \mu(F(X)) & \leq \mu(F_1(X_1 \times X_2 \times \dots \times X_n) \times \\ & F_2(X_1 \times X_2 \times \dots \times X_n) \times \dots \\ & \times F_n(X_1 \times X_2 \times \dots \times X_n)) \\ & = \max_k \mu(F_k(X_1 \times X_2 \times \dots \times X_n)) \\ & \leq \max_k \varphi(\max_i \mu(X_i)) \\ & \leq \varphi(\mu(X)) \end{aligned}$$

Therefore, all the conditions of Theorem 1 are satisfied, hence by that theorem F has a fixed point, i.e., there exist $(x_1^*, x_2^*, \dots, x_n^*) \in C_1 \times C_2 \times \dots \times C_n$ such that

$$\begin{aligned} (x_1^*, x_2^*, \dots, x_n^*) & = F(x_1^*, x_2^*, \dots, x_n^*) \\ & = (F_1(x_1^*, x_2^*, \dots, x_n^*), \\ & F_2(x_1^*, x_2^*, \dots, x_n^*), \dots, F_n(x_1^*, x_2^*, \dots, x_n^*)) \end{aligned}$$

which gives (5) and the proof is complete.

In (Aghajani et al., 2013, Lemma 2.1) Aghajani et al. proved that for every nondecreasing and upper semicontinuous function $\varphi: \mathbb{R}_+ \rightarrow \mathbb{R}_+$, the following two conditions are equivalent:

- (I) $\lim_{n \rightarrow \infty} \varphi^n(t) = 0$ for any $t > 0$.
- (II) $\varphi(t) < t$ for any $t > 0$.

So the results of Theorem 3 remain true if (I) is replaced by (II). The following result is a generalization of similar results by Aghajani et al., and Rzepecki in (1982).

Corollary 1. Let C_i be a nonempty, bounded, convex and closed subset of a Banach space E_i ($i = 1, 2, \dots, n$), and let $F_i: C_1 \times C_2 \times \dots \times C_n \rightarrow C_i$ ($i = 1, 2, \dots, n$) be a continuous operator such that $\mu(F_i(X_1 \times X_2 \times \dots \times X_n)) \leq k \max_j \mu(X_j)$ for

any subset X_i of C_i , where μ_i is an arbitrary measure of noncompactness on E_i and $k \in [0, 1)$. Then there exist $(x_1^*, x_2^*, \dots, x_n^*) \in C_1 \times C_2 \times \dots \times C_n$ such that for all $1 \leq i \leq n$

$$F_i(x_1^*, x_2^*, \dots, x_n^*) = x_i^*.$$

Proof: Take $\varphi(t) = kt$ in Theorem 3.

As a consequence of Theorem 3 we obtain the following corollary, which plays an important role in the next section.

Corollary 2. Let C_i be a nonempty, bounded, convex and closed subset of a Banach space E_i ($i = 1, 2, \dots, n$) and let $F_i, G_i: C_1 \times C_2 \times \dots \times C_n \rightarrow E_i$ and $T_i: C_1 \times C_2 \times \dots \times C_n \rightarrow C_i$ be operators such that

$$\begin{aligned} & \|F_i(x_1, x_2, \dots, x_n) - F_i(y_1, y_2, \dots, y_n)\| \\ & \leq \varphi(\max_j \|x_j - y_j\|) \end{aligned}$$

and

$$\begin{aligned} & \|T_i(x_1, x_2, \dots, x_n) - T_i(y_1, y_2, \dots, y_n)\| \leq \\ & \|F_i(x_1, x_2, \dots, x_n) - F_i(y_1, y_2, \dots, y_n)\| \quad (6) \\ & + \Phi(\|G_i(x_1, x_2, \dots, x_n) - G_i(y_1, y_2, \dots, y_n)\|) \end{aligned}$$

for any $x_i, y_i \in C_i$ ($i = 1, 2, \dots, n$), where $\varphi, \Phi: \mathbb{R}_+ \rightarrow \mathbb{R}_+$ are nondecreasing and right continuous functions such that $\lim_{n \rightarrow \infty} \varphi^n(t) = 0$ for each $t \geq 0$ and $\Phi(0) = 0$. Assume that G_i are compact, continuous operators for $i = 1, 2, \dots, n$. Then there exists $(x_1^*, x_2^*, \dots, x_n^*) \in C_1 \times C_2 \times \dots \times C_n$ such that for all $1 \leq i \leq n$ $T_i(x_1^*, x_2^*, \dots, x_n^*) = x_i^*$.

Proof: Let X_j be an arbitrary subset of C_j ($j = 1, 2, \dots, n$) and fixed $1 \leq i \leq n$. By the definition of Kuratowski measure of noncompactness, for every $\varepsilon > 0$ there exist S_1, \dots, S_m such that $X_1 \times X_2 \times \dots \times X_n \subseteq \bigcup_{k=1}^m S_k$, $diam(F_i(S_k)) < \alpha(F_i(X_1 \times X_2 \times \dots \times X_n)) + \varepsilon$ and $diam(G_i(S_k)) < \varepsilon$.

Let us fix arbitrary $1 \leq k \leq m$. Then for every $p, q \in S_k$ we have

$$\begin{aligned} & \|T_i(p) - T_i(q)\| \leq \\ & \|F_i(p) - F_i(q)\| + \Phi(\|G_i(p) - G_i(q)\|). \end{aligned}$$

Thus, by properties of Φ we obtain $diam(T_i(S_k)) \leq diam(F_i(S_k)) + \Phi(diam(G_i(S_k)))$, $diam(T_i(S_k)) \leq \alpha(F_i(X_1 \times \dots \times X_n)) + \varepsilon + \Phi(\varepsilon)$

and since ε was arbitrarily and Φ and φ are nondecreasing and right continuous functions, the following estimate holds

$$\begin{aligned} & \alpha(T_i(X_1 \times X_2 \times \dots \times X_n)) \leq \\ & \alpha(F_i(X_1 \times X_2 \times \dots \times X_n)). \end{aligned} \quad (7)$$

Now we show that T_i satisfies (4) for ($i = 1, 2, \dots, n$). To do this fix arbitrary $x_j, y_j \in X_j$ ($j = 1, 2, \dots, n$). Then

$$\begin{aligned} & \|F_i(x_1, x_2, \dots, x_n) - F_i(y_1, y_2, \dots, y_n)\| \\ & \leq \varphi(\max_j \|x_j - y_j\|) \\ & \leq \varphi(\max_j diam X_j) \end{aligned}$$

so

$$diam F_i(X_1 \times X_2 \times \dots \times X_n) \leq \varphi(\max_j diam X_j)$$

Therefore from the definition of Kuratowski measure of noncompactness we get

$$\alpha(F_i(X_1 \times X_2 \times \dots \times X_n)) \leq \varphi(\max_j \alpha(X_j)). \quad (8)$$

Using (8) in (7) we deduce $\alpha(T_i(X_1 \times X_2 \times \dots \times X_n)) \leq \varphi(\max_j \alpha(X_j))$.

Also, from condition (6), T_i is a continuous operator, now an application of Theorem 3 completes the proof.

4. Application

In this section, as an application of Theorem 3 we prove the existence of solutions for a large class of systems of functional integral equations of Volterra type in two variables.

Let $BC(\mathbb{R}_+ \times \mathbb{R}_+)$ be the Banach space of all bounded and continuous functions on $\mathbb{R}_+ \times \mathbb{R}_+$ equipped with the standard norm

$$\|x\| = \sup\{|x(t, s)| : t, s \geq 0\}.$$

For any nonempty bounded subset X of $BC(\mathbb{R}_+ \times \mathbb{R}_+)$, $x \in X$, $L > 0$ and $\varepsilon > 0$ let

$$\omega^L(x, \varepsilon) = \sup\{|x(t, s) - x(u, v)| : t, s,$$

$$u, v \in [0, L], |t - u| \leq \varepsilon, |s - v| \leq \varepsilon\},$$

$$\omega^L(X, \varepsilon) = \sup\{\omega^L(x, \varepsilon) : x \in X\},$$

and

$$\omega_0^L(X) = \lim_{\varepsilon \rightarrow 0} \omega^L(X, \varepsilon),$$

$$\omega_0(X) = \lim_{L \rightarrow \infty} \omega_0^L(X),$$

$$X(t, s) = \{x(t, s) : x \in X\}$$

$$\mu(X) = \omega_0(X) + \limsup_{\|(t,s)\| \rightarrow \infty} diam X(t, s) \quad (9)$$

where $\|(t, s)\| = \max(t, s)$. Similar to Banas et al., (1980) (cf. also Banas et al., (2003)), it can be shown that the function μ is a measure of oncompactness in the space $BC(\mathbb{R}_+ \times \mathbb{R}_+)$ (in the sense of Definition 1).

Theorem 4. Assume that the following conditions are satisfied:

(i) $\beta_i, \zeta_i : R_+ \rightarrow R_+$ ($i=1,2$) are continuous functions.

(ii) $f_i : R_+ \times R_+ \times R^{n+1} \rightarrow R$ ($i=1,2,\dots,n$) is continuous. Moreover there exist nondecreasing and right continuous functions $\varphi, \Phi_i : R_+ \rightarrow R_+$ such that $\varphi(t) < t$ for all $t \geq 0$, $\Phi_i(0) = 0$ ($i=1,2,\dots,n$) and

$$|f_i(t, s, x_1, \dots, x_{n+1}) - f_i(t, s, y_1, \dots, y_{n+1})| \leq \varphi(\max_{1 \leq j \leq n} |x_j - y_j|) + \Phi_i(m_i(t, s) |x_{n+1} - y_{n+1}|) \quad (10)$$

where $m_i : R_+ \times R_+ \rightarrow R_+$ is a continuous function for $i=1,2,\dots,n$.

(iii) $M := \sup\{|f_i(t, s, 0, \dots, 0)| : t, s \in R_+, 1 \leq i \leq n\} < \infty$.

(iv) $g_i : R_+ \times R_+ \times R_+ \times R_+ \times R^n \rightarrow R$ are continuous functions for $i=1,2,\dots,n$ and

$$D := \sup\{m_i(t, s) \left| \int_0^{\zeta_i(s)} \int_0^{\beta_i(t)} g_i(t, s, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw \right| : t, s \in R_+, 1 \leq i \leq n, x_1, x_2, \dots, x_n \in BC(R_+ \times R_+) \} < \infty. \quad (11)$$

Moreover,

$$\lim_{\|(t,s)\| \rightarrow \infty} m_i(t, s) \left| \int_0^{\zeta_i(s)} \int_0^{\beta_i(t)} [g_i(t, s, v, w, x_1(v, w), \dots, x_n(v, w)) - g_i(t, s, v, w, y_1(v, w), \dots, y_n(v, w))] dv dw \right| = 0$$

uniformly with respect to $x_1, \dots, x_n, y_1, \dots, y_n \in BC(R_+ \times R_+)$ for all $1 \leq i \leq n$.

(v) There exists a positive solution r_0 to the inequality $\varphi(r) + M + \max_i \{\Phi_i(D)\} \leq r$.

Then the system of functional integral equations (1) has at least one solution in the space $BC(R_+ \times R_+)^n$.

The proof relies on the following useful observation.

Lemma 1. Assume that g_i satisfy the hypothesis (iv) for $i=1,2,\dots,n$, then $G_i : BC(R_+ \times R_+)^n \rightarrow BC(R_+ \times R_+)$ defined by

$$G_i((x_j)_{j=1}^n)(t, s) = m_i(t, s) \int_0^{\zeta_i(s)} \int_0^{\beta_i(t)} g_i(t, s, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw \quad (12)$$

are compact and continuous operators for $i=1,2,\dots,n$.

Proof: Let us fix arbitrarily $1 \leq i \leq n$. First notice that the continuity of $G_i((x_j)_{j=1}^n)(t, s)$ for any fixed $(x_j)_{j=1}^n \in BC(R_+ \times R_+)^n$ is obvious. Moreover, by (12), G_i is well defined on $BC(R_+ \times R_+)^n$. Now we show that G_i is a continuous operator on $BC(R_+ \times R_+)^n$. To verify this, take $((x_j)_{j=1}^n) \in BC(R_+ \times R_+)^n$ and $\varepsilon > 0$ arbitrarily. Moreover take $((y_j)_{j=1}^n) \in BC(R_+ \times R_+)^n$ with $\|x_j - y_j\| < \varepsilon$. Then we have

$$\begin{aligned} & |G_i((x_j)_{j=1}^n)(t, s) - G_i((y_j)_{j=1}^n)(t, s)| \\ & \leq m_i(t, s) \left| \int_0^{\zeta_i(s)} \int_0^{\beta_i(t)} [g_i(t, s, v, w, x_i(v, w), \dots, x_n(v, w)) - g_i(t, s, v, w, y_1(v, w), \dots, y_n(v, w))] dv dw \right| \end{aligned}$$

So, using condition (iv) we can find a $T > 0$ such that for $\|(t, s)\| > T$

$$|G_i((x_j)_{j=1}^n)(t, s) - G_i((y_j)_{j=1}^n)(t, s)| \leq \varepsilon$$

and if $t, s \in [0, T]$, then

$$|G_i((x_j)_{j=1}^n)(t, s) - G_i((y_j)_{j=1}^n)(t, s)| \leq m_T \beta_T \zeta_T \mathcal{G}_{i,T}(\varepsilon),$$

where

$$\beta_T = \sup\{\beta_i(t) : t \in [0, T], 1 \leq i \leq n\},$$

$$\zeta_T = \sup\{\zeta_i(t) : t \in [0, T], 1 \leq i \leq n\},$$

$m_T = \sup\{m_i(t, s) : t, s \in [0, T], 1 \leq i \leq n\}$,
 $\mathcal{G}_{i,T}(\varepsilon) = \sup\{|g_i(t, s, v, w, x_1, \dots, x_n) - g_i(t, s, v, w, y_1, \dots, y_n)| : t, s \in [0, T], v \in [0, \beta_T], w \in [0, \zeta_T], x_i, y_i \in [-b, b], |x_i - y_i| \leq \varepsilon\}$
 with $b = \max_i \|k_i\| + \varepsilon$. By using the continuity of g_i on the compact set $[0, T] \times [0, T] \times [0, \beta_T] \times [0, \zeta_T] \times [-b, b]^n$, we have $\mathcal{G}_{i,T}(\varepsilon) \rightarrow 0$ as $\varepsilon \rightarrow 0$. Thus, G_i is a continuous function on $BC(R_+ \times R_+)^n$. To finish the proof we only need to verify that G_i is compact. Let X_1, \dots, X_n be nonempty and bounded subset of $BC(R_+ \times R_+)$, and assume that $T > 0$ and $\varepsilon > 0$ are arbitrary constants. Let $t_1, t_2, s_1, s_2 \in [0, T]$, with $|t_2 - t_1| \leq \varepsilon$, $|s_2 - s_1| \leq \varepsilon$ and $x_i \in X_i$. we have
 $|G_i((x_j)_{j=1}^n)(t_2, s_2) - G_i((x_j)_{j=1}^n)(t_1, s_1)| \leq$
 $\leq |m_i(t_2, s_2) \int_0^{\zeta_i(s_2)} \int_0^{\beta_i(t_2)} g_i(t_2, s_2, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw$
 $- m_i(t_2, s_2) \int_0^{\zeta_i(s_2)} \int_0^{\beta_i(t_2)} g_i(t_1, s_1, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw |$
 $+ |m_i(t_2, s_2) \int_0^{\zeta_i(s_2)} \int_0^{\beta_i(t_2)} g_i(t_1, s_1, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw$
 $- m_i(t_2, s_2) \int_0^{\zeta_i(s_2)} \int_0^{\beta_i(t_1)} g_i(t_1, s_1, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw |$
 $+ |m_i(t_2, s_2) \int_0^{\zeta_i(s_2)} \int_0^{\beta_i(t_1)} g_i(t_1, s_1, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw$
 $- m_i(t_1, s_1) \int_0^{\zeta_i(s_1)} \int_0^{\beta_i(t_1)} g_i(t_1, s_1, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw |$
 $\leq m_T \left[\int_0^{\zeta_i(s_2)} \int_0^{\beta_i(t_2)} [g_i(t_2, s_2, v, w, x_1(v, w), \dots, x_n(v, w))$
 $- g_i(t_1, s_1, v, w, x_1(v, w), \dots, x_n(v, w))] dv dw |$
 $+ m_T \left| \int_0^{\zeta_i(s_2)} \int_{\beta_i(t_1)}^{\beta_i(t_2)} g_i(t_1, s_1, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw |$
 $+ m_T \left| \int_{\zeta_i(s_1)}^{\zeta_i(s_2)} \int_0^{\beta_i(t_1)} g_i(t_1, s_1, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw | \right.$
 $\leq m_T (\zeta_T \beta_T \omega_r^T(g_i, \varepsilon) + \zeta_T U_r^T \omega^T(\beta_i, \varepsilon) + \beta_T U_r^T \omega^T(\zeta_i, \varepsilon)),$ (13)
 where $r = \sup\{\|k_i\| : x_i \in X_i, 1 \leq i \leq n\}$,
 $\omega_r^T(g_i, \varepsilon) = \sup\{|g_i(t_1, s_1, v, w, x_1, \dots, x_n) - g_i(t_2, s_2, v, w, x_1, \dots, x_n)| : t_1, t_2, s_1, s_2 \in [0, T], |t_2 - t_1| \leq \varepsilon, |s_2 - s_1| \leq \varepsilon, v \in [0, \beta_T], w \in [0, \zeta_T], x_i \in [-r, r]\}$,
 $\omega^T(\beta_i, \varepsilon) = \sup\{|\beta_i(a) - \beta_i(b)| : a, b \in [0, T], |a - b| \leq \varepsilon\}$,
 $\omega^T(\zeta_i, \varepsilon) = \sup\{|\zeta_i(a) - \zeta_i(b)| : a, b \in [0, T], |a - b| \leq \varepsilon\}$,
 $U_r^T = \sup\{|g_i(t, s, v, w, x_1, \dots, x_n)| : t, s \in [0, T], v \in [0, \beta_T], w \in [0, \zeta_T], x_i \in [-r, r]\}$.
 Since x_i was arbitrary element of $X_i, i = 1, \dots, n$ in (13), we obtain
 $\omega^T(G_i(X_1 \times \dots \times X_n), \varepsilon) \leq m_T (\zeta_T \beta_T \omega_r^T(g_i, \varepsilon) + \zeta_T U_r^T \omega^T(\beta_i, \varepsilon) + \beta_T U_r^T \omega^T(\zeta_i, \varepsilon))$
 and by the uniform continuity of g_i, β_i and ζ_i on the compact sets $[0, T] \times [0, T] \times [0, \beta_T] \times [0, \zeta_T] \times [-r, r]^n, [0, T]$ and $[0, T]$ respectively, we have
 $\omega_r^T(g_i, \varepsilon) \rightarrow 0, \omega^T(\beta_i, \varepsilon) \rightarrow 0$ and $\omega^T(\zeta_i, \varepsilon) \rightarrow 0$ as $\varepsilon \rightarrow 0$. Therefore we obtain
 $\omega_0^T(G_i(X_1 \times \dots \times X_n)) = 0$
 and, finally
 $\omega_0(G_i(X_1 \times \dots \times X_n)) = 0.$ (14)
 On the other hand, for all $x_i, y_i \in X_i (i = 1, \dots, n)$ and $t, s \in R_+$ we get

$- g_i(t_1, s_1, v, w, x_1(v, w), \dots, x_n(v, w))] dv dw |$
 $+ m_T \left| \int_0^{\zeta_i(s_2)} \int_{\beta_i(t_1)}^{\beta_i(t_2)} g_i(t_1, s_1, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw |$
 $+ m_T \left| \int_{\zeta_i(s_1)}^{\zeta_i(s_2)} \int_0^{\beta_i(t_1)} g_i(t_1, s_1, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw | \right.$
 $\leq m_T (\zeta_T \beta_T \omega_r^T(g_i, \varepsilon) + \zeta_T U_r^T \omega^T(\beta_i, \varepsilon) + \beta_T U_r^T \omega^T(\zeta_i, \varepsilon)),$ (13)
 where $r = \sup\{\|k_i\| : x_i \in X_i, 1 \leq i \leq n\}$,
 $\omega_r^T(g_i, \varepsilon) = \sup\{|g_i(t_1, s_1, v, w, x_1, \dots, x_n) - g_i(t_2, s_2, v, w, x_1, \dots, x_n)| : t_1, t_2, s_1, s_2 \in [0, T], |t_2 - t_1| \leq \varepsilon, |s_2 - s_1| \leq \varepsilon, v \in [0, \beta_T], w \in [0, \zeta_T], x_i \in [-r, r]\}$,
 $\omega^T(\beta_i, \varepsilon) = \sup\{|\beta_i(a) - \beta_i(b)| : a, b \in [0, T], |a - b| \leq \varepsilon\}$,
 $\omega^T(\zeta_i, \varepsilon) = \sup\{|\zeta_i(a) - \zeta_i(b)| : a, b \in [0, T], |a - b| \leq \varepsilon\}$,
 $U_r^T = \sup\{|g_i(t, s, v, w, x_1, \dots, x_n)| : t, s \in [0, T], v \in [0, \beta_T], w \in [0, \zeta_T], x_i \in [-r, r]\}$.
 Since x_i was arbitrary element of $X_i, i = 1, \dots, n$ in (13), we obtain
 $\omega^T(G_i(X_1 \times \dots \times X_n), \varepsilon) \leq m_T (\zeta_T \beta_T \omega_r^T(g_i, \varepsilon) + \zeta_T U_r^T \omega^T(\beta_i, \varepsilon) + \beta_T U_r^T \omega^T(\zeta_i, \varepsilon))$
 and by the uniform continuity of g_i, β_i and ζ_i on the compact sets $[0, T] \times [0, T] \times [0, \beta_T] \times [0, \zeta_T] \times [-r, r]^n, [0, T]$ and $[0, T]$ respectively, we have
 $\omega_r^T(g_i, \varepsilon) \rightarrow 0, \omega^T(\beta_i, \varepsilon) \rightarrow 0$ and $\omega^T(\zeta_i, \varepsilon) \rightarrow 0$ as $\varepsilon \rightarrow 0$. Therefore we obtain
 $\omega_0^T(G_i(X_1 \times \dots \times X_n)) = 0$
 and, finally
 $\omega_0(G_i(X_1 \times \dots \times X_n)) = 0.$ (14)
 On the other hand, for all $x_i, y_i \in X_i (i = 1, \dots, n)$ and $t, s \in R_+$ we get

$$\begin{aligned}
 & |G_i(x_1, \dots, x_n)(t, s) - G_i(y_1, \dots, y_n)(t, s)| \leq \\
 & \leq m_i(t, s) \left| \int_0^{\zeta_i(s)} \int_0^{\beta_i(t)} \right. \\
 & [g_i(t, s, v, w, x_1(v, w), \dots, x_n(v, w)) - \\
 & g_i(t, s, v, w, y_1(v, w), \dots, y_n(v, w))] dv dw \mid \\
 & \text{where} \\
 & \theta_i(t, s) = \sup \{ m_i(t, s) \mid \int_0^{\zeta_i(s)} \int_0^{\beta_i(t)} \\
 & [g_i(t, s, v, w, x_1(v, w), \dots, x_n(v, w)) \\
 & - g_i(t, s, v, w, y_1(v, w), \dots, y_n(v, w))] \\
 & dv dw \mid : x_1, y_1, \dots, x_n, y_n \in BC(R_+ \times R_+) \}. \\
 & \text{Thus}
 \end{aligned}$$

$$\text{diam}G_i(X_1 \times \dots \times X_n)(t, s) \leq \theta_i(t, s). \tag{15}$$

Taking $t, s \rightarrow \infty$ in the inequality (15), then using (iv) we arrive at

$$\limsup_{\|(t,s)\| \rightarrow \infty} \text{diam}G_i(X_1 \times \dots \times X_n)(t, s) = 0. \tag{16}$$

Further, combining (14) and (16) we get

$$\begin{aligned}
 & \limsup_{t,s \rightarrow \infty} \text{diam}G_i(X_1 \times \dots \times X_n)(t, s) \\
 & + \omega_0(G_i(X_1 \times \dots \times X_n)) = 0 \tag{17}
 \end{aligned}$$

or, equivalently

$$\mu(G_i(X_1 \times \dots \times X_n)) = 0.$$

Therefore, G_i is compact and the proof is complete.

Theorem 5. Under the assumptions (i)-(v), Eq. (1) has at least one solution in $BC(R_+ \times R_+)^n$.

Proof: We define the operators $F_i, T_i : BC(R_+ \times R_+)^n \rightarrow BC(R_+ \times R_+)$ by

$$F_i(x_1, \dots, x_n)(t, s) = x_i(t, s)$$

and

$$T_i(x_1, \dots, x_n)(t, s) = f_i(t, s, x_1(t, s), \dots, x_n(t, s), \int_0^{\zeta_i(s)} \int_0^{\beta_i(t)} g_i(t, s, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw).$$

Using conditions (i)-(iv), for arbitrary fixed $t, s \in R_+$, we have

$$\begin{aligned}
 & |T_i(x_1, \dots, x_n)(t, s)| \leq \\
 & \leq f_i(t, s, x_1(t, s), \dots, x_n(t, s), \\
 & \int_0^{\zeta_i(s)} \int_0^{\beta_i(t)} g_i(t, s, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw) \\
 & - f_i(t, s, 0, \dots, 0) \mid
 \end{aligned}$$

$$\begin{aligned}
 & + |f_i(t, s, 0, \dots, 0)| \\
 & \leq \phi(\max_i |x_i(t, s)|) + \Phi_i(m_i(t, s) \mid \int_0^{\zeta_i(s)} \int_0^{\beta_i(t)} \\
 & g_i(t, s, v, w, x_1(v, w), \dots, x_n(v, w)) dv dw \mid) \\
 & + |f_i(t, s, 0, \dots, 0)| \\
 & \leq \phi(\max_i |x_i(t, s)|) + M + \Phi_i(D).
 \end{aligned}$$

Thus,

$$\|T(x_1, \dots, x_n)\| \leq \phi(\max_i \|x_i\|) + M + \Phi_i(D) \tag{18}$$

and $T(x_1, \dots, x_n) \in BC(R_+ \times R_+)$ for any $(x_1, \dots, x_n) \in BC(R_+ \times R_+)^n$. Due to Inequality (18) and using (v), the function T_i maps $\bar{B}_{r_0} \times \bar{B}_{r_0} \times \dots \times \bar{B}_{r_0}$ into B_{r_0} . Also, applying (10) and definitions of G_i, F_i and T_i , it is easy to verify that

$$\begin{aligned}
 & |T_i(x_1, \dots, x_n)(t, s) - T_i(y_1, \dots, y_n)(t, s)| \leq \\
 & \phi(|F_i(x_1, \dots, x_n)(t, s) - F_i(y_1, \dots, y_n)(t, s)|) \\
 & + \Phi_i(|G_i(x_1, \dots, x_n)(t, s) - \\
 & G_i(y_1, \dots, y_n)(t, s)|).
 \end{aligned}$$

Thus, T_i satisfies (6), $i = 1, \dots, n$, now an application of Corollary 3.3 completes the proof. The following examples illustrate the applicability of our results.

Example 6. Consider the following system of functional integral equations

$$\left\{ \begin{aligned}
 & x_1(t, s) = \frac{ts}{(ts+1)(|x_1(t, s)|+1)} + \\
 & \frac{1}{e^{ts}} \arctan\left(\int_0^t \int_0^s \frac{v^3 \cos(x_1(v, w)) + e^w \sin(x_2^4(v, w))}{(2 + \sin(x_1(v, w)))} \right. \\
 & \left. dv dw \right) \\
 & x_2(t, s) = \sin(ts) + \frac{|x_2(t, s)|}{|x_2(t, s)|+1} + \\
 & \int_0^{\sqrt{t}} \int_0^{\sqrt{s}} \frac{\sqrt{1 + \sin^2(ux_1(u, v))} + ts(uv)^{11}(1 + x_2^4(u, v))}{(1+t^7s^7)(1+x_2^4(u, v))} \\
 & dudv
 \end{aligned} \right. \tag{19}$$

Eq. (19) is a special case of Eq. (1) where

$$\beta_1(t) = \zeta_1(t) = t, \beta_2(t) = \zeta_2(t) = \sqrt{t},$$

$$f_1(t, s, x_1, x_2, z) = \frac{ts}{(ts+1)(|x_1|+1)} + \frac{1}{e^{ts}} \arctan(z),$$

$$f_2(t, s, x_1, x_2, z) = \sin(ts) + \frac{|x_2|}{|x_2|+1} + z,$$

$$g_1(t, s, v, w, x_1, x_2) = \frac{v^3 \cos(x_1) + e^w \sin(x_2^4)}{(2 + \sin(x_1))},$$

$$g_2(t, s, v, w, x_1, x_2) = \frac{\sqrt{1 + \sin^2(vx_1)} + ts(vw)^{11}(1 + x_2^4)}{(1 + t^7s^7)(1 + x_2^4)}.$$

From the definitions of β_i, ζ_i, f_i and f_2 , hypothesis (i) and (iv) of Theorem 5 are obviously satisfied. Also we have

$$|f_1(t, s, x_1, x_2, z_1) - f_1(t, s, y_1, y_2, z_2)| \leq$$

$$\leq \left| \frac{ts}{(ts+1)(|x_1|+1)} + \frac{1}{e^{ts}} \arctan(z_1) - \frac{ts}{(ts+1)(|y_1|+1)} - \frac{1}{e^{ts}} \arctan(z_2) \right|$$

$$\leq \frac{|x_1 - y_1|}{(|x_1|+1)(|y_1|+1)} + \frac{1}{e^{ts}} |z_1 - z_2|$$

$$\leq \frac{|x_1 - y_1|}{|x_1 - y_1|+1} + \frac{1}{e^{ts}} |z_1 - z_2|$$

and similarly

$$|f_2(t, s, x_1, x_2, z_1) - f_2(t, s, y_1, y_2, z_2)| \leq$$

$$\frac{|x_2 - y_2|}{|x_2 - y_2|+1} + |z_1 - z_2|.$$

Thus, by taking $m_1(t, s) = \frac{1}{e^{ts}}, m_2(t, s) = 1,$

$$\varphi(t) = \frac{t}{t+1} \quad \text{and} \quad \Phi_1(t) = \Phi_2(t) = t, \quad \text{the}$$

functions f_1 and f_2 satisfy assumption (ii) of Theorem 5. Also, g_1 and g_2 are continuous on $R_+ \times R_+ \times R_+ \times R_+ \times R \times R$ and since

$$\left| \frac{1}{e^{ts}} \int_0^t \int_0^s \frac{v^3 \cos(x_1(v, w)) + e^w \sin(x_2^4(v, w))}{(2 + \sin(x_1(v, w)))} \right.$$

$dvdw \leq$

$$\left. \left| \int_0^t \int_0^s \frac{v^3 + e^w}{e^{ts}} dvdw \right| \right.$$

$$\leq \frac{\frac{s^4 t}{4} + e^t s - s}{e^{ts}}$$

and

$$\left| \int_0^{\sqrt{t}} \int_0^{\sqrt{s}} \frac{\sqrt{1 + \sin^2(ux_1(u, v))} + ts(uv)^{11}(1 + x_2^4(u, v))}{(1 + t^7s^7)(1 + x_2^4(u, v))} \right.$$

$dudv \leq$

$$\left. \left| \int_0^{\sqrt{t}} \int_0^{\sqrt{s}} \frac{\sqrt{2}}{1 + t^7s^7} + \frac{ts(uv)^{11}}{1 + t^7s^7} dudv \right| \right.$$

$$\leq \frac{\sqrt{2ts} + (ts)^{\frac{13}{2}}}{1 + t^7s^7}$$

for all $t, s \in R_+$, so we obtain

$D \leq$

$$\sup \left\{ \frac{\frac{s^4 t}{4} + e^t s - s}{e^{ts}} + \frac{\sqrt{2ts} + (ts)^{\frac{13}{2}}}{1 + t^7s^7} : s, t \in R_+ \right\}$$

$< \infty.$

Moreover,

$$\lim_{\|(t,s)\| \rightarrow \infty} \frac{1}{e^{ts}} \int_0^t \int_0^s \frac{v^3 \cos(x_1(v, w)) + e^w \sin(x_2^4(v, w))}{(2 + \sin(x_1(v, w)))} dvdw = 0,$$

$$\lim_{\|(t,s)\| \rightarrow \infty} \frac{1}{e^{ts}} \int_0^t \int_0^s$$

$$\frac{v^3 \cos(x_1(v, w)) + e^w \sin(x_2^4(v, w))}{(2 + \sin(x_1(v, w)))} -$$

$$\frac{v^3 \cos(y_1(v, w)) + e^w \sin(y_2^4(v, w))}{(2 + \sin(y_1(v, w)))}$$

$$dvdw = 0$$

and

$$\lim_{\|(t,s)\| \rightarrow \infty} \int_0^{\sqrt{t}} \int_0^{\sqrt{s}} \left[\frac{\sqrt{1 + \sin^2(ux_1(u, v))} + ts(uv)^{11}(1 + x_2^4(u, v))}{(1 + t^7s^7)(1 + x_2^4(u, v))} - \frac{\sqrt{1 + \sin^2(uy_1(u, v))} + ts(uv)^{11}(1 + y_2^4(u, v))}{(1 + t^7s^7)(1 + y_2^4(u, v))} \right]$$

$$dudv = 0,$$

uniformly with respect to $x_1, x_2, y_1, y_2 \in BC(R_+)$, which show that assumption (iv) is satisfied. Furthermore, we have

$$M = \sup \{ |f_i(t, s, 0, 0, 0)| : t, s \in R_+, i = 1, 2 \}$$

$$= \sup \left\{ \frac{ts}{ts+1}, \sin(ts), t, s \in R_+ \right\} = 1.$$

So, taking $r_0 \geq 2 + D$ then we see that assumptions (iii) and (v) of Theorem 5 are satisfied. Hence by that theorem the system of integral equations (19) has at least one solution in the space $BC(R_+ \times R_+)^2$.

References

- Agarwal, R. P., & O'Regan, D. (2000). Singular Volterra integral equations. *Applied Mathematics Letters*, 13, 115–120.
- Agarwal, R. P., Benchohra, M., & Seba, D. (2009). On the application of measure of noncompactness to the existence of solutions for fractional differential equations. *Results in Mathematics*, 55, 221–230.
- Aghajani, A., Banas, J., & Jalilian, Y. (2011). Existence of solution for a class of nonlinear Volterra singular integral equations. *Computer & Mathematics with Applications*, 62, 1215–1227.
- Aghajani, A., & Jalilian, Y. (2010). Existence and global attractivity of solutions of a nonlinear functional integral equation. *Communications in Nonlinear Science and Numerical Simulation*, 15, 3306–3312.
- Aghajani, A., & Jalilian, Y. (2011). Existence of Nondecreasing Positive Solutions for a system of singular integral equations. *Mediterranean Journal of Mathematics*, 8, 563–576.
- Aghajani, A., Banas, J., & Sabzali, N. (2013). Some generalizations of Darbo fixed point theorem and applications. *Bulletin of the Belgian Mathematical Society-Simon Stevin*, 20(2), 345–358.
- Aghajani, A., & Sabzali, N. (2014). Existence of coupled fixed points via measure of Noncompactness and applications. *Journal of Nonlinear and Convex Analysis*, 15(5), 941–952.
- Banas, J., & Dhage, B. C. (2008). Global asymptotic stability of solutions of a functional integral equation. *Nonlinear Analysis: Theory, Methods & Applications*, 69, 1945–1952.
- Banas, J., & Goebel, K. (1980). Measures of Noncompactness in Banach Spaces. *Lecture Notes in Pure & Applied Mathematics*, vol. 60, Dekker, New York.
- Banas, J., & Rzepka, B. (2003). An application of a measure of noncompactness in the study of asymptotic Stability. *Applied Mathematics Letters*, 16, 1–6.
- Banas, J., & Rzepka, B. (2009). Nondecreasing solutions of a quadratic singular Volterra integral equation. *Mathematical & Computer Modelling*, 49, 488–496.
- Banas, J., O'Regan, D., & Sadarangani, K. (2009). On solutions of a quadratic hammerstein integral equation on an unbounded interval. *Dynamic Systems & Applications*, 18, 251–264.
- Chang, S. S., Cho, Y. J., & Huang N. J. (1996). Coupled fixed point theorems with applications. *Journal of the Korean Mathematical Society*, 33(3), 575–585.
- Darwish, M. A., & Ntouyas, S. K. (2011). Existence of monotone solutions of a perturbed quadratic integral equation of Urysohn type. *Nonlinear Studies*, 18, 155–165.
- Darwish, M. A., & Ntouyas, S. K. (2009). Monotonic solutions of a perturbed quadratic fractional integral equation. *Nonlinear Analysis: Theory, Methods & Applications*, 71, 5513–5521.
- Darwish, M. A. (2008). On monotonic solutions of a quadratic integral equation with supremum. *Dynamic Systems & Applications*, 17, 539–550.
- Darwish, M. A. (2007). On a singular quadratic integral equation of Volterra type with supremum. *The Abdus Salam International Centre for Theoretical Physics, Trieste, Italy*, 1–13.
- Dhage, B. C., & Bellale, S. S. (2008). Local asymptotic stability for nonlinear quadratic functional integral equations. *Electronic Journal Qualitative Theory of Differential Equations*, 10, 1–13.
- Djebali, S., O'Regan, D., & Sahnoun, Z. (2011). On the solvability of some operator equations and inclusions in Banach spaces with the weak topology. *Applied Analysis*, 15, 125–140.
- Estrada, R., & Kanwal, R. P. (1999). *Singular Integral Equations*, Birkhäuser, Boston.
- Hu, X., & Yan, J. (2006). The global attractivity and asymptotic stability of solution of a nonlinear integral equation. *Journal of Mathematical Analysis & Applications*, 321, 147–56.
- Liu, Z., & Kang, SM. (2007). Existence and asymptotic stability of solutions to functional-integral equation. *Taiwanese Journal of Mathematics*, 11(1), 87–96.
- Liu, L., Guo, F., Wu, C., & Wu, Y. (2005). Existence theorems of global solutions for nonlinear Volterra type integral equations in Banach spaces. *Journal of Mathematical Analysis & Applications*, 638–49.
- Kominek, Z., & Matkowski, J. (1974). On the existence of a convex solutions of the functional equation $\varphi(x) = h(x, \varphi(f(x)))$. *Annales Polonici Mathematici*, 30, 1–4.
- Kordylewski, J., & Kuczma, M. (1960). On some linear functional equation. *ibidem*, 9, 119–136.
- Kuczma, M. (1960). On the form of solutions of some functional equation. *ibidem*, 9, 55–63.
- Kuratowski, K. (1930). Sur les espaces. *Fundamenta Mathematicae*, 15, 301–309.
- Matkowsski, J., & Zdun, C. (1974). Solutions of bounded variation of a linear functional equation. *Aequationes mathematicae*, 11, 223–235.
- Mursaleen, M., & Mohiuddine, S. A. (2012). Applications of measures of noncompactness to the infinite system of differential equations in L_p spaces. *Nonlinear Analysis: Theory, Methods & Applications*, 75, 2111–2115.
- Mursaleen, M., & Alotaibi, A. (2012). Infinite system of differential equations in some spaces. *Abstract & Applied Analysis*, doi:10.1155/2012/863483.
- Olszowy, L. (2009). On some measures of noncompactness in the Fréchet spaces of continuous functions. *Nonlinear Analysis*, 71, 5157–5163.
- O'Regan, D. (1998). Fixed-point theory for weakly sequentially continuous mappings. *Mathematical & Computer Modelling*, 27(5), 1–14.
- O'Regan, D. (1996). Fixed-point theory for the sum of two operators. *Applied Mathematics Letters*, 9(1), 1–8.
- Rzepecki, B. (1982). On measure of noncompactness in topological vector spaces, *Commentationes Mathematicae Universitatis Carolinae*, 23, 105–116.
- Szep, A. (1971). Existence theorems for weak solutions of ordinary differential equations in reflexive Banach spaces. *Studia Scientiarum Mathematicarum Hungarica*, 6, 197–203.